Dense Prediction on Sequences with Time-Dilated Convolutions for Speech Recognition

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Convolutional Neural Networks for LVCSR

2-stage training scheme: Cross-Entropy (XE) vs Sequence Training (ST), test time



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Semantic segmentation



Semantic segmentation



Depth map prediction





Depth map prediction

Semantic segmentation

Framewise classification = dense pixelwise prediction!

Dense Pixelwise Prediction with Convnets

Patch-by-patch vs efficient



(a) Patch-by-patch scanning for CNN based pixelwise classification



Prediction Map Target Label Map

Sequential: Framewise classification

Spliced (bad) vs efficient (good)



B Efficient convolutional evaluation. Dense prediction viewpoint.

Sequential: Framewise classification

Spliced (bad) vs efficient (good)



B Efficient convolutional evaluation. Dense prediction viewpoint.

Can we have time-pooling into the CNN?

Time-pooling

XE: Toy CNN with pooling in time



Time-pooling

ST: Downsampling is a problem



$\mathsf{Time-pooling} \to \mathsf{Time-dilated} \ \mathsf{convolutions}$

ST: Solution to downsampling



Based on Spatial dilated convolution [Li et al., 2014, Yu and Koltun, 2016] or OverFeat [Sermanet et al., 2013]

With dense prediction viewpoint for ST

• CNNs with strided pooling in time

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 - Better performance [Sercu et al., 2016, Sercu and Goel, 2016]

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 - Efficient convolutional evaluation
 - Batch Normalization
- End-to-end models with CNNs
 - Can accept downsampling
 - But this allows to pool more than acceptable amount of downsampling

Result on switchboard

Big n-gram LM

	SWB	CH
IBM 2015 DNN+RNN+CNN	8.8 †	15.3 †
IBM 2016 RNN+VGG+LSTM	7.6 †	13.7 †
MSR 2016 ResNet *	8.6	14.8
MSR 2016 LACE *	8.3	14.8
MSR 2016 BLSTM *	8.7	16.2
VGG + BN	8.1	15.9
VGG + BN + pool	7.7	14.5

- † model combination / * smaller LM
- Note: simple language model. Followed by: LM rescoring

Figures sources and references

- Slide 3 (Semantic Segmentation)
 [Long et al., 2015] Figure 6
- Slide 3 (Depth map prediction)
 [Eigen et al., 2014] Figure 4
- Slide 4 (Patches)
 [Li et al., 2014] Figure 1

Eigen, D., Puhrsch, C., and Fergus, R. (2014).

Depth map prediction from a single image using a multi-scale deep network.

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Thank you! Questions?

Here's a cake which doesn't have anything to do with the talk

